

Forward Modeling of Magnetic Fields

From last time we had:

①
$$\Phi_m(P) = \frac{\mu_0}{4\pi} \int_R \vec{M} \cdot \vec{\nabla}_Q \left(\frac{1}{r} \right) dv \quad \leftarrow \begin{matrix} \text{scalar pot due} \\ \text{to magnetiz}^n \\ \vec{M} \end{matrix}$$

and \vec{B} can be obtained from $\vec{B} = -\nabla\Phi_m$.

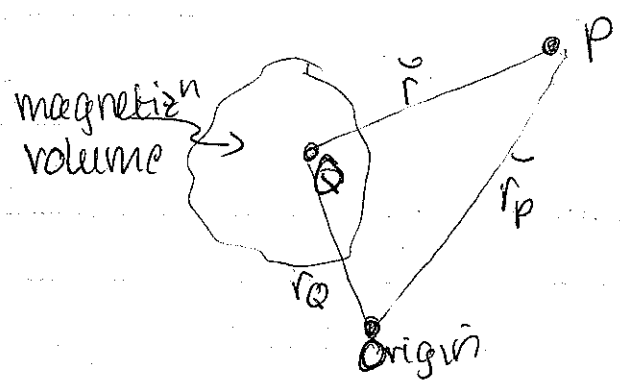
⇒ Thus for a generalized magnetizⁿ distribution we can compute Φ_m and \vec{B}

Special Case: Forward Modeling for regions of constant ρ and \vec{M}

If \vec{M} is constant, then ① can be written as

$$\Phi_m(P) = \frac{-\mu_0}{4\pi} \vec{M} \cdot \vec{\nabla}_P \int_R \frac{1}{r} dv \quad \text{--- ②}$$

since $\vec{\nabla}_Q \left(\frac{1}{r} \right) = -\vec{\nabla}_P \left(\frac{1}{r} \right)$



since

$$\vec{\nabla}_P \left(\frac{1}{r} \right) = \frac{\vec{r}_{QP}}{r^3} = \frac{\vec{r}_P - \vec{r}_Q}{r^3}$$

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We showed previously that the gravitational potential for a volume/body of constant density is given by

$$\Phi_g(P) = \cancel{G} G \int_R \frac{\rho}{r} dv = G \rho \int_R \frac{1}{r} dv$$

②

$$\Rightarrow \text{so } \boxed{\int_R \frac{1}{r} dv = \frac{\Phi_g}{G\rho}} \text{ ----- } \textcircled{3}$$

Substituting ③ into ② gives

$$\Phi_m = \frac{-\mu_0}{4\pi} \vec{M} \cdot \vec{\nabla}_p \left(\frac{\Phi_g}{G\rho} \right) = \frac{-\mu_0 M}{4\pi G\rho} (\hat{m} \cdot \vec{\nabla}_p \Phi_g)$$

where $\vec{M} = M \hat{m}$

\hat{m} \rightarrow unit vector in \vec{M} direction

But since $\vec{\nabla} \Phi_g = \vec{g}$

$$\Rightarrow \boxed{\Phi_m = \frac{-\mu_0 M}{4\pi G\rho} \hat{m} \cdot \vec{g}} \text{ ----- } \textcircled{4}$$

This known as Poisson's relation

\Rightarrow Thus if $\frac{\Delta \rho}{\rho}$ is constant, Φ_m can be calculated from the gravity field.

typically it is the density anomaly in a region that is of interest

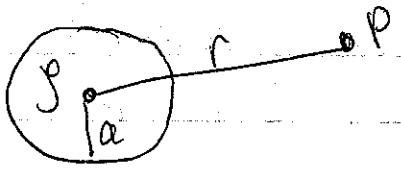
----- surface

$\Delta \rho, \vec{M}$

ALSO : This allows us to compute pseudo-gravity maps from magnetic maps. This can be useful in interpreting magnetic data for geologic structure.

Example #1 :

Magnetic field of a Uniformly Magnetized Sphere



$$\vec{g} = \frac{-G(\text{mass sphere})}{r^2} \hat{r}$$

$$= -\frac{4}{3} \pi a^3 \rho G \frac{\hat{r}}{r^2}$$

- Sphere, radius a
- constant density ρ , and



constant magnetization, \vec{M}

$$\Phi_M = \frac{\mu_0 M}{4\pi \rho G} \hat{m} \cdot \vec{g}$$

gamma on next line should be G

$$= \frac{\mu_0 M}{4\pi \rho G} \left(-\frac{4}{3} \pi a^3 \rho G \right) \hat{m} \cdot \frac{\hat{r}}{r^2}$$

$$= \frac{\mu_0}{4\pi} \left(\frac{4}{3} \pi a^3 M \right) \hat{m} \cdot \frac{\hat{r}}{r^2}$$

and substitute $\vec{m} = \frac{4}{3} \pi a^3 \vec{M}$

↓
magnetic dipole
centered @ center
of sphere

↓ magnetization

so $\Phi_M = \frac{\mu_0}{4\pi} \frac{\vec{m} \cdot \hat{r}}{r^2}$ ----- (5)

So a uniformly magnetized sphere has the same magnetic field outside the body as a point dipole @ the center of the sphere.

Analogy with gravity (\vec{g} due to uniform density sphere \equiv to treat due to point mass @ center)

(4)

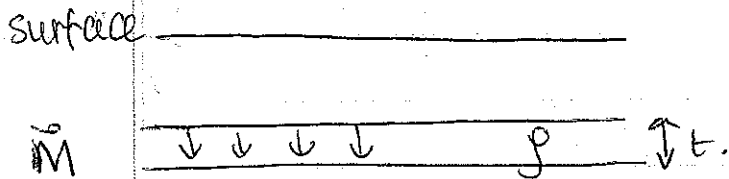
Remark : Note that measuring the field due to a uniformly magnetized sphere allows us to determine only the

- centre of the sphere (dipole location)
- strength of the dipole, $\frac{4}{3} \pi a^3 M$

We can't uniquely determine a , or M without more information.

The same non-uniqueness problem arises w/ gravity data.

Example # 2 : Magnetic field due to a uniformly magnetized layer



see later in course

$$\vec{g} = 2\pi G \rho t \hat{z}$$

Suppose $\vec{M} = M \hat{z}$ (vertical).

$$\Phi_m = \frac{-\mu_0}{4\pi \rho G} \vec{M} \cdot \vec{g} = \frac{-\mu_0}{4\pi \rho G} 2\pi G \rho t \hat{z} \cdot (M \hat{z})$$

$$\Rightarrow \boxed{\Phi_m = -\frac{\mu_0 t M}{2}}$$

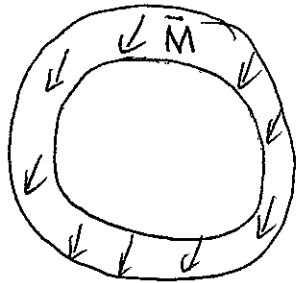
← magnetic potential is constant.

$$\text{Thus } \boxed{\vec{B} = -\nabla \Phi_m = 0} \quad \text{--- (6)}$$

Hence the magnetic field of a uniformly magnetized slab is zero. Hence we cannot detect such a structure from magnetic field measurements.

(5)

As we will see later, the same conclusion holds for a uniformly magnetized ^{spherical} shell.



→ $\vec{B}_{\text{outside the shell}} = 0$.

This is known as Runcorn's theorem.

Runcorn used this, together with early observations of the Moon's magnetic field (that indicated $\vec{B} \approx 0$) to argue that the following two hypotheses could not be distinguished:

- 1) The Moon does not currently have a global (core dynamo) field, and has never had one
- 2) The Moon does not currently have a global field but had one early in its history that resulted in a uniformly magnetized crustal shell.

The important ~~the~~ point is that non-zero magnetic field measurements at or above a planet's surface indicate magnetization contrasts laterally.

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