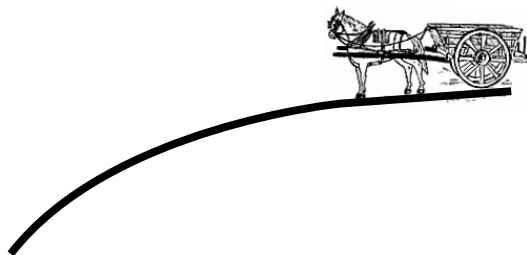
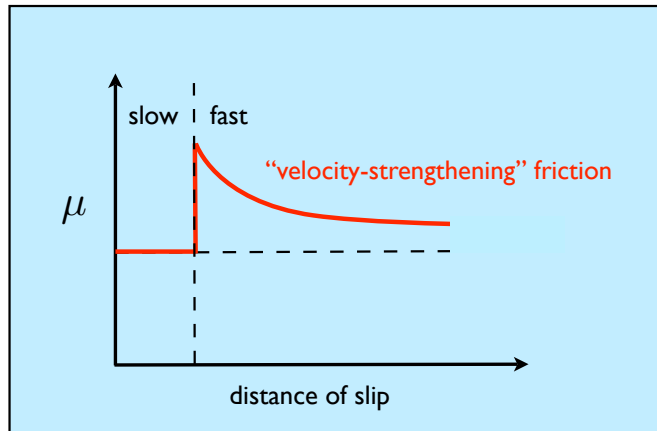




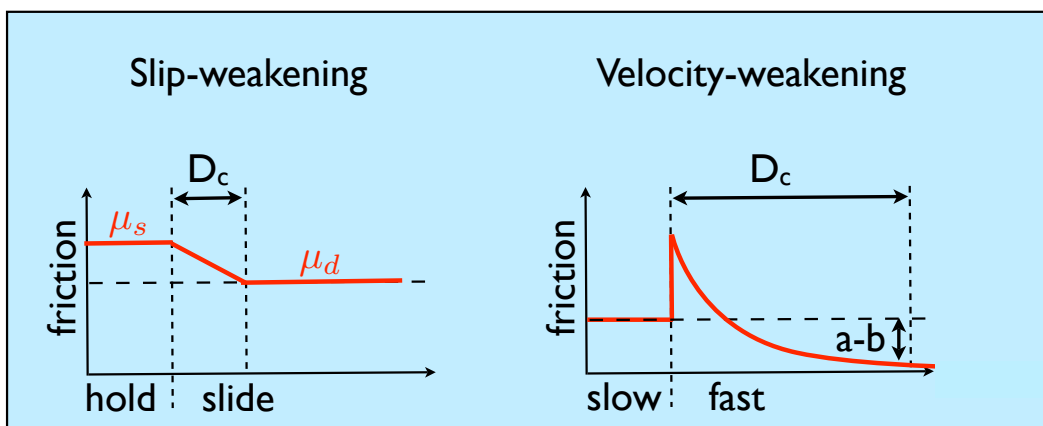
μ increases during sliding

- faster sliding --> stronger fault
--> slows sliding
- leads to stable slip:
no earthquakes can start
- “velocity-strengthening” friction



μ decreases during sliding:

- instability may be possible
- “velocity weakening”
or
“slip weakening”

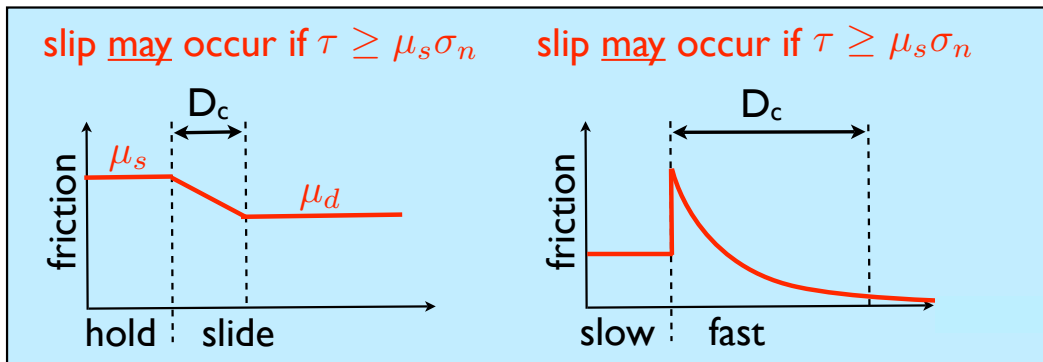


With velocity-weakening or slip-weakening friction:

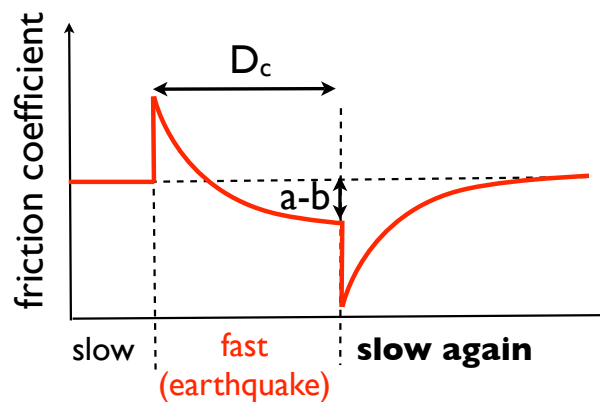
- fault eventually does stop sliding (stick-slip, Friday)
- fault is **still** not always unstable
 - > you saw this with one case on Friday - which one?

Slip-weakening

Velocity-weakening

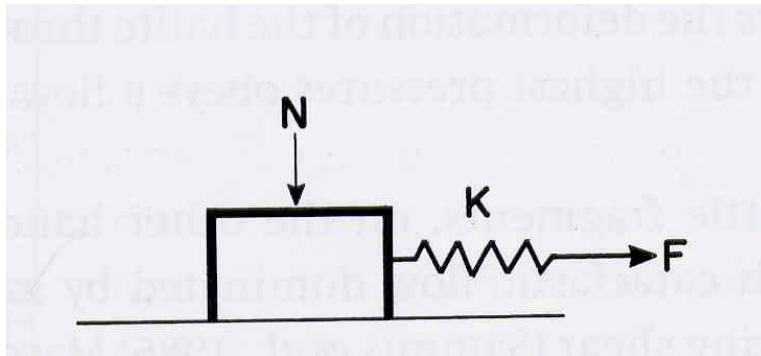


Only velocity-weakening friction addresses how the fault recovers its frictional strength between earthquakes

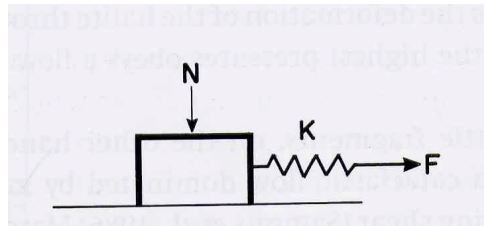


D_c is the distance over which steady-state friction is re-established at the new sliding velocity

Spring-slider activity: slip stopped because...



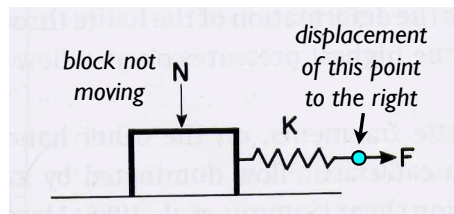
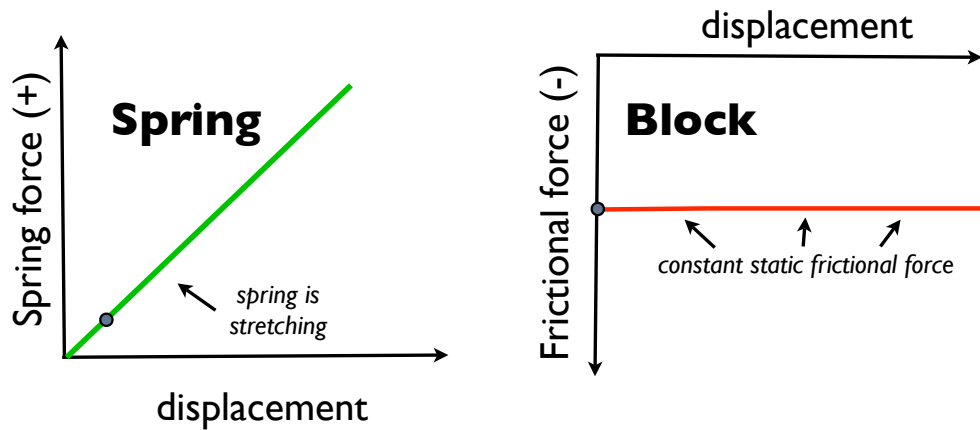
Today: a closer look at the conditions leading to instability, and why the earthquake ends.



This is a battle between the shear force pulling the block and the friction force resisting it

$$\tau \times A = k \times x = F_{spring} = \sigma_n \times A \times \mu = N \times \mu = F_{friction}$$

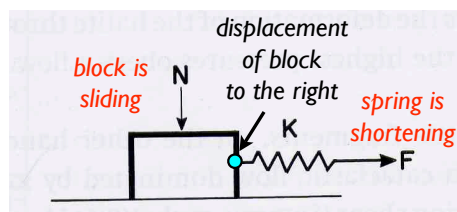
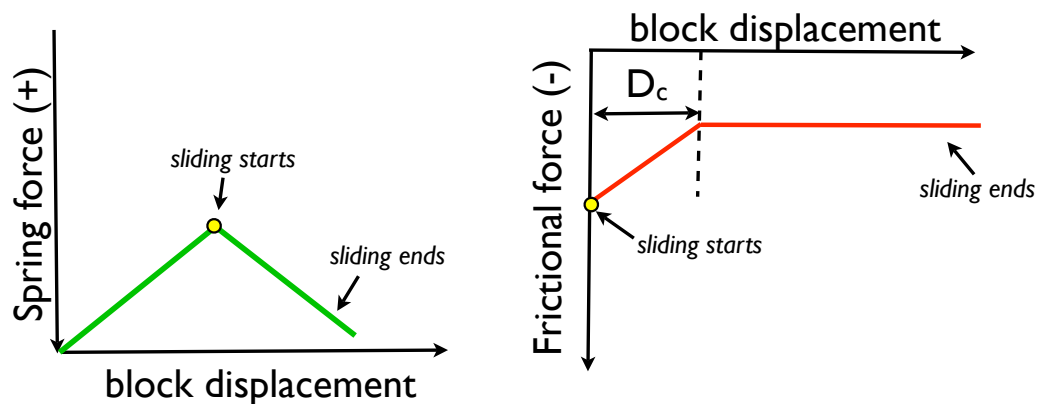
Before the block started to slide...



to the right =
+ x direction



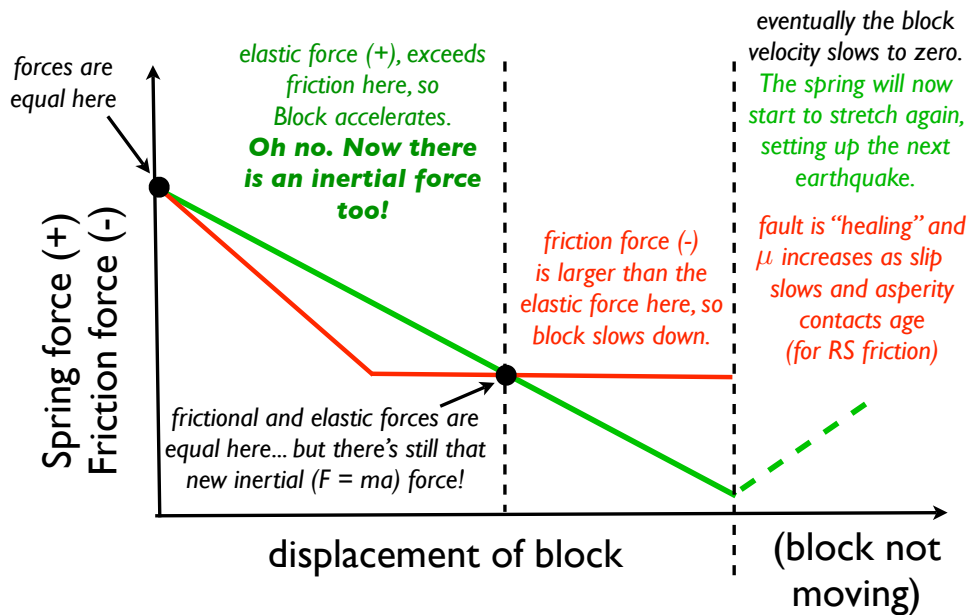
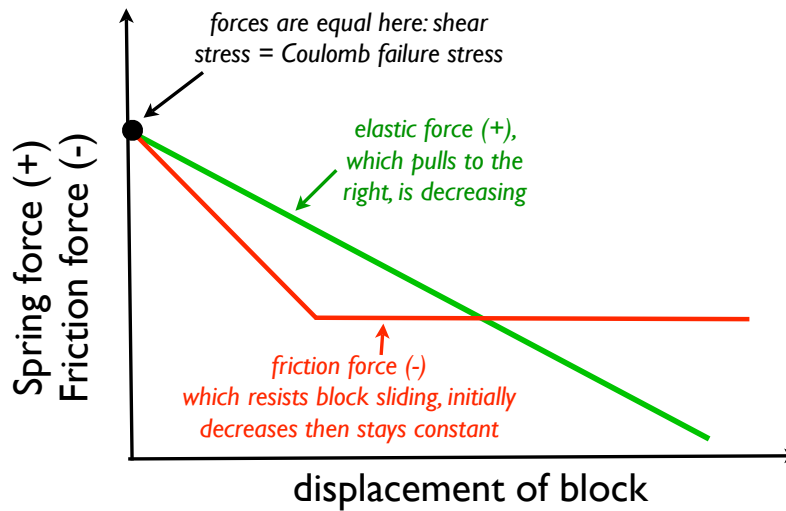
Now block sliding begins... assume
slip weakening friction



to the right =
+ x direction



Redraw this with absolute values of forces so the lines cross where $|\text{friction force}| = |\text{spring force}|$



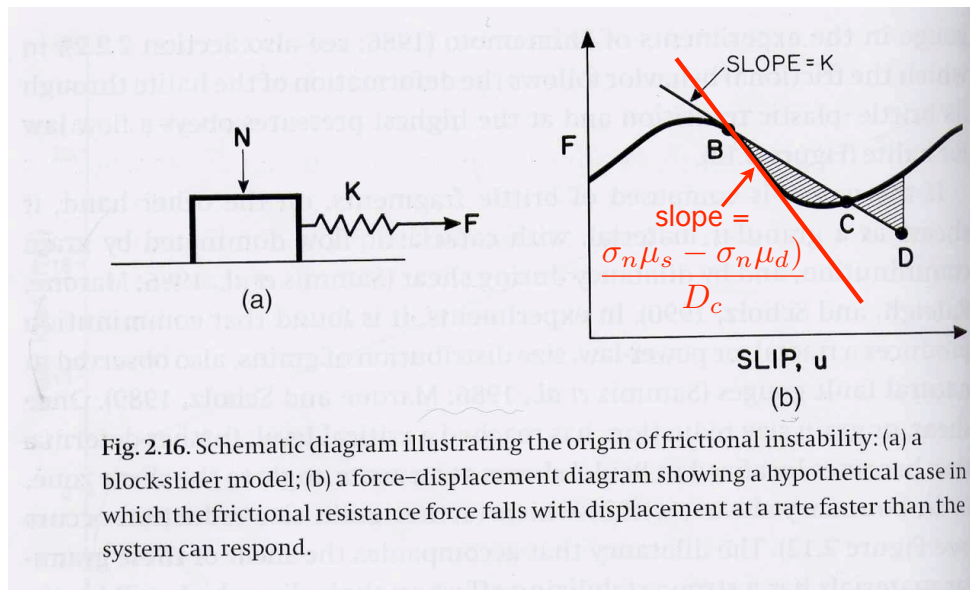
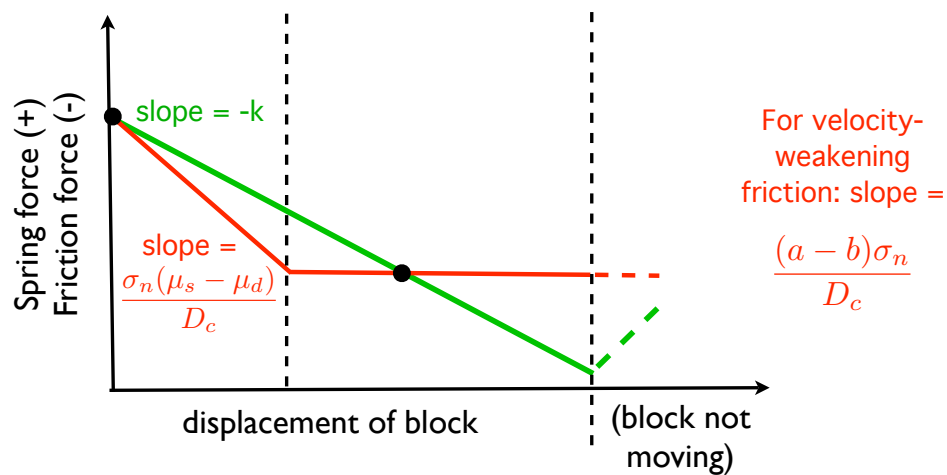


Fig. 2.16. Schematic diagram illustrating the origin of frictional instability: (a) a block-slider model; (b) a force-displacement diagram showing a hypothetical case in which the frictional resistance force falls with displacement at a rate faster than the system can respond.

From Scholz, 1998



Instability happens if friction decrease during sliding is steeper than elastic force decrease...

Instability if

$$k < \frac{\sigma_n(b-a)}{D_c}$$

Instability happens if friction decrease during sliding is steeper than elastic force decrease...

Instability if

$$k < \frac{\sigma_n(b-a)}{D_c}$$

Friday, what happened in the “stiff spring” experiment?

Instability happens if friction decrease during sliding is steeper than elastic force decrease...

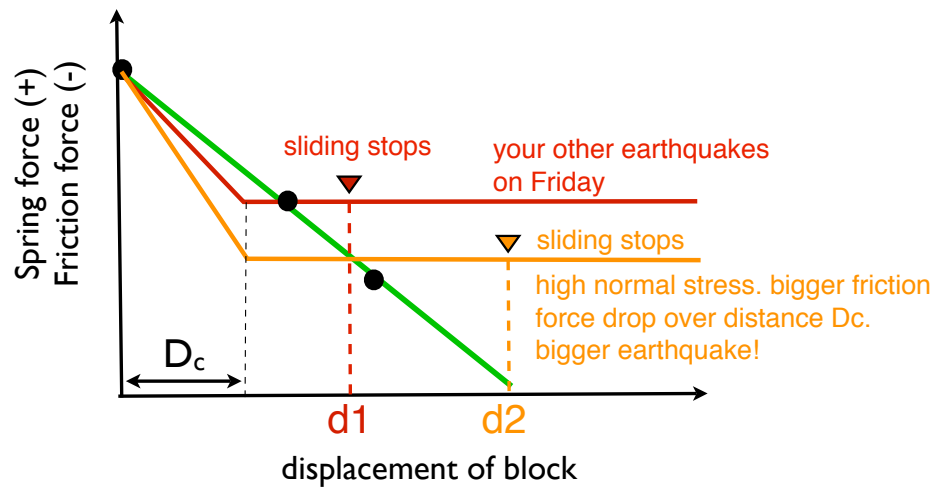
Instability if

$$k < \frac{\sigma_n(b-a)}{D_c}$$

- stiff spring?
- high normal stress?
- weak spring?
- low normal stress?

What about those big earthquakes you made by adding weight to the block?

- high normal stress (added a weight)
- no change to the spring stiffness (same old spring)



What does this mean in the Earth?

$$k < \frac{\sigma_n(b-a)}{D_\varepsilon}$$

D_c and (a-b) : from lab experiments

$$\sigma_n: \text{from (approx.) } \rho g h$$

k? ... this needs to relate slip to elastic stress decrease along a slipping patch of the fault

Equation for stiffness k for a small, elliptical crack is:

$$k = \frac{G}{(1 - \nu)L}$$

G = shear modulus

ν = Poisson's ratio

L = length of slipping area

$$k < \frac{\sigma_n(b-a)}{D_c}$$

$$\frac{G}{(1-\nu)L} < \frac{\sigma_n(b-a)}{D_c}$$

k = crack stiffness
 G = shear modulus
 ν = Poisson's ratio
 L = length of slipping area
 $(b-a)$ = friction weakening parameter
 σ_n = normal stress
 D_c = friction weakening distance

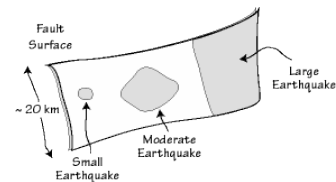
$$L > \frac{D_c G}{(1-\nu)(b-a)\sigma_n}$$

This tells us that the slipping patch of fault must be bigger than a critical size to go unstable, even for a velocity weakening fault

The slipping patch of fault must be bigger than a critical size to go unstable

Determine the **minimum earthquake size** (magnitude and moment) assuming: $G=30$ GPa, normal stress = 50 MPa, $b-a = 0.01$, $\nu = 0.25$, and $D_c = 10^{-4}$ m.

$$L > \frac{D_c G}{(1-\nu)(b-a)\sigma_n}$$



Get L and then get moment and moment magnitude using equations from Feb 23 notes. Assume offset (slip) is 0.01 times L .